

Midterm is on Thursday!

Project presentations are
May 17th, 22nd and 24th

Next week there is a strike on campus.
Class is therefore cancelled on Tuesday.

Please work on your presentations instead!

REVIEW

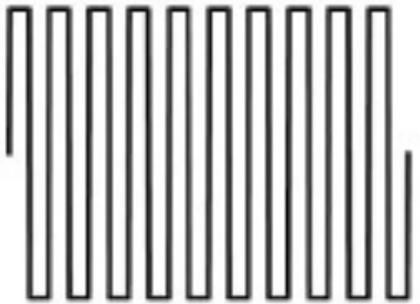
From results on practice midterm:
Half of the class needs another
review!

Spatial frequency

(a) High-frequency square wave



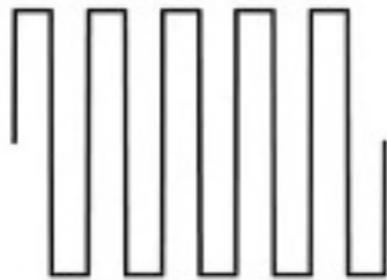
10 cycles



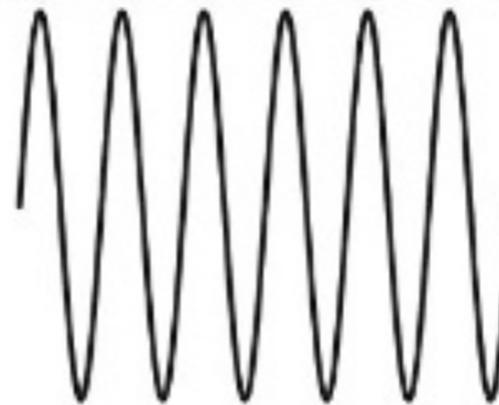
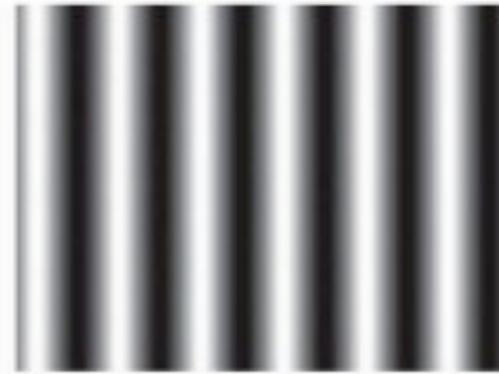
(b) Low-frequency square wave



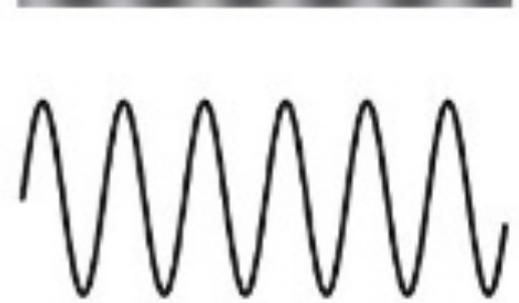
5 cycles



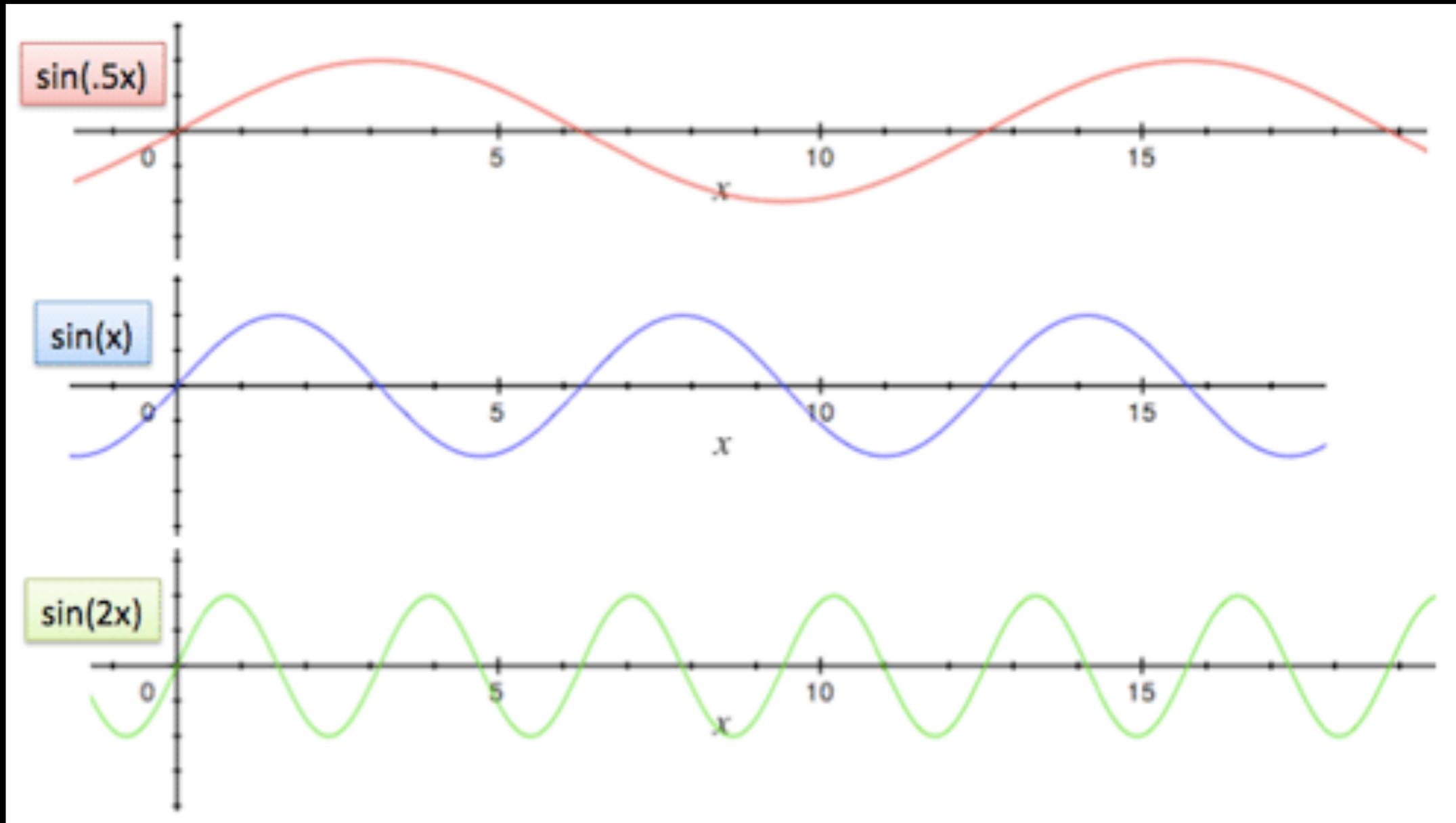
(c) High-contrast sinusoidal spatial grid



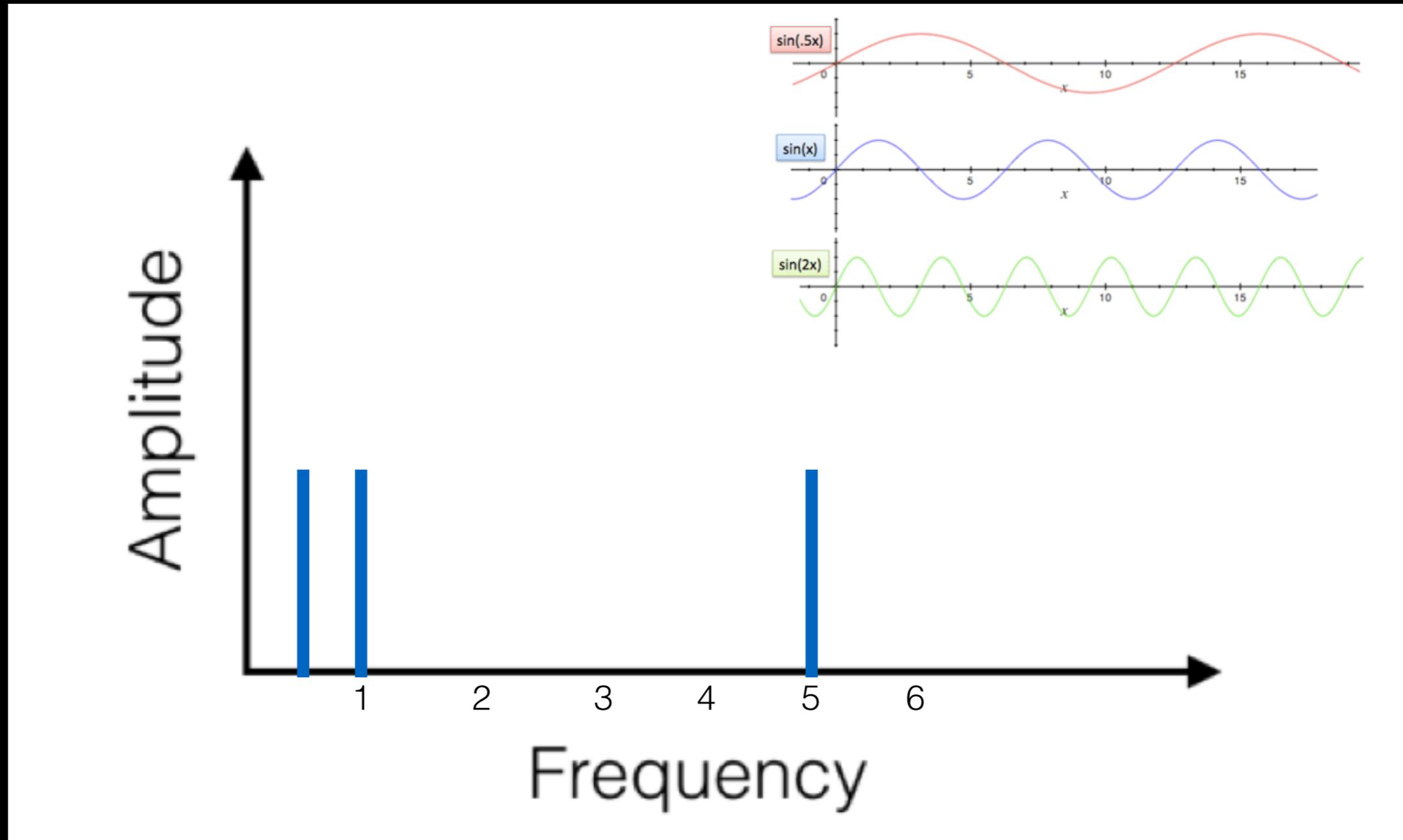
(d) Low-contrast sinusoidal spatial grid



1D Frequency Spectrum



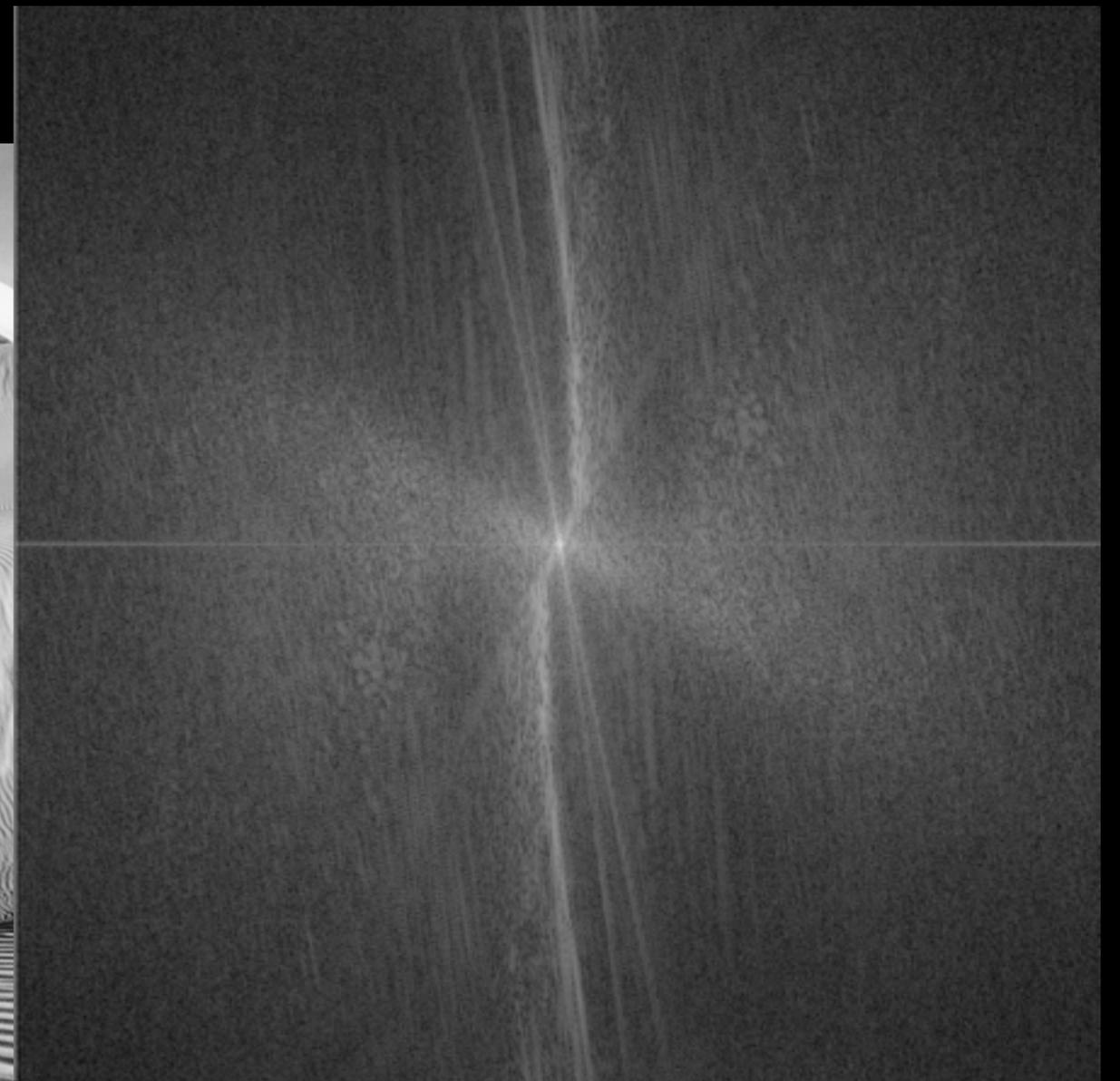
Frequency spectrum





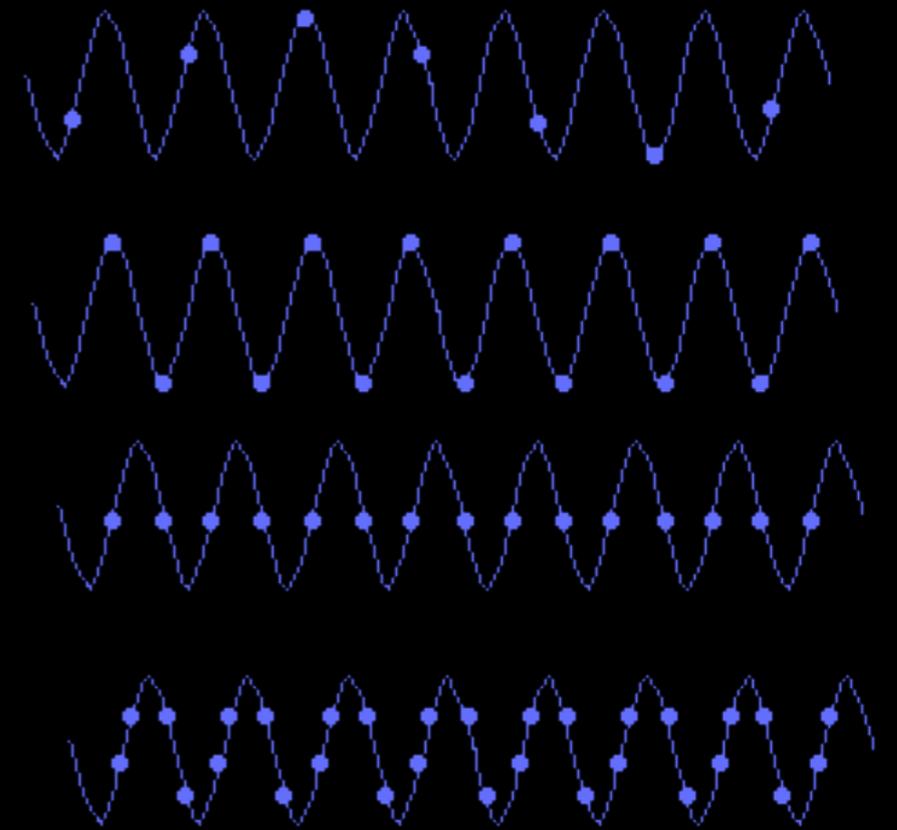
2D Fourier Transform Power Spectrum

- 2D Fourier transform of the *Dunes* photograph

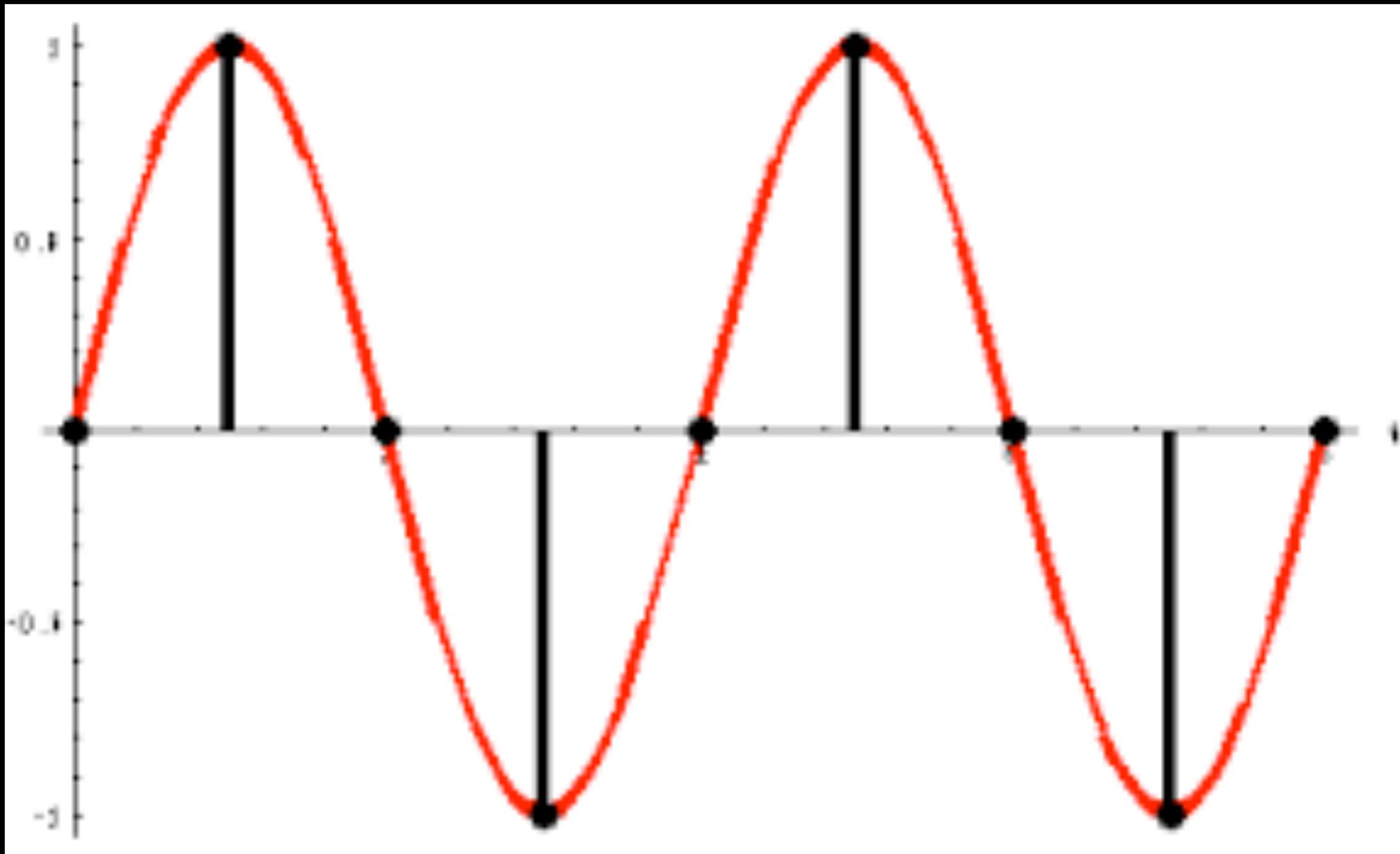


Sampling

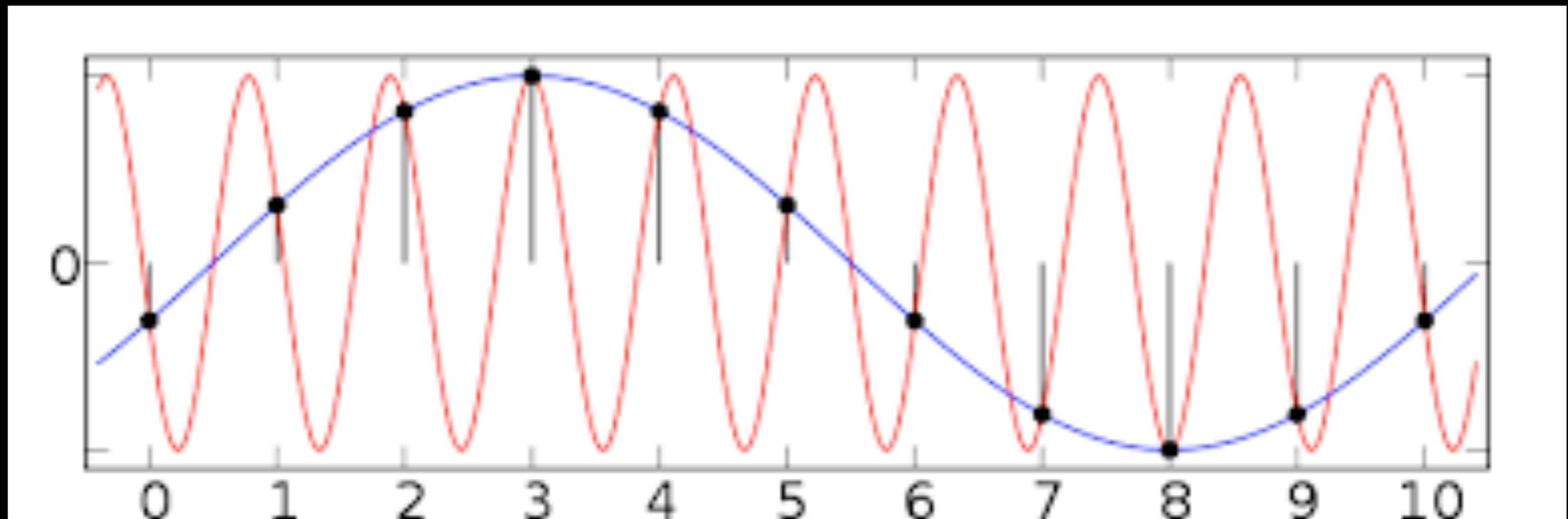
- Both in space and time
- Select acquisition speed
- Select sensor size / Optical magnification
- Aliasing



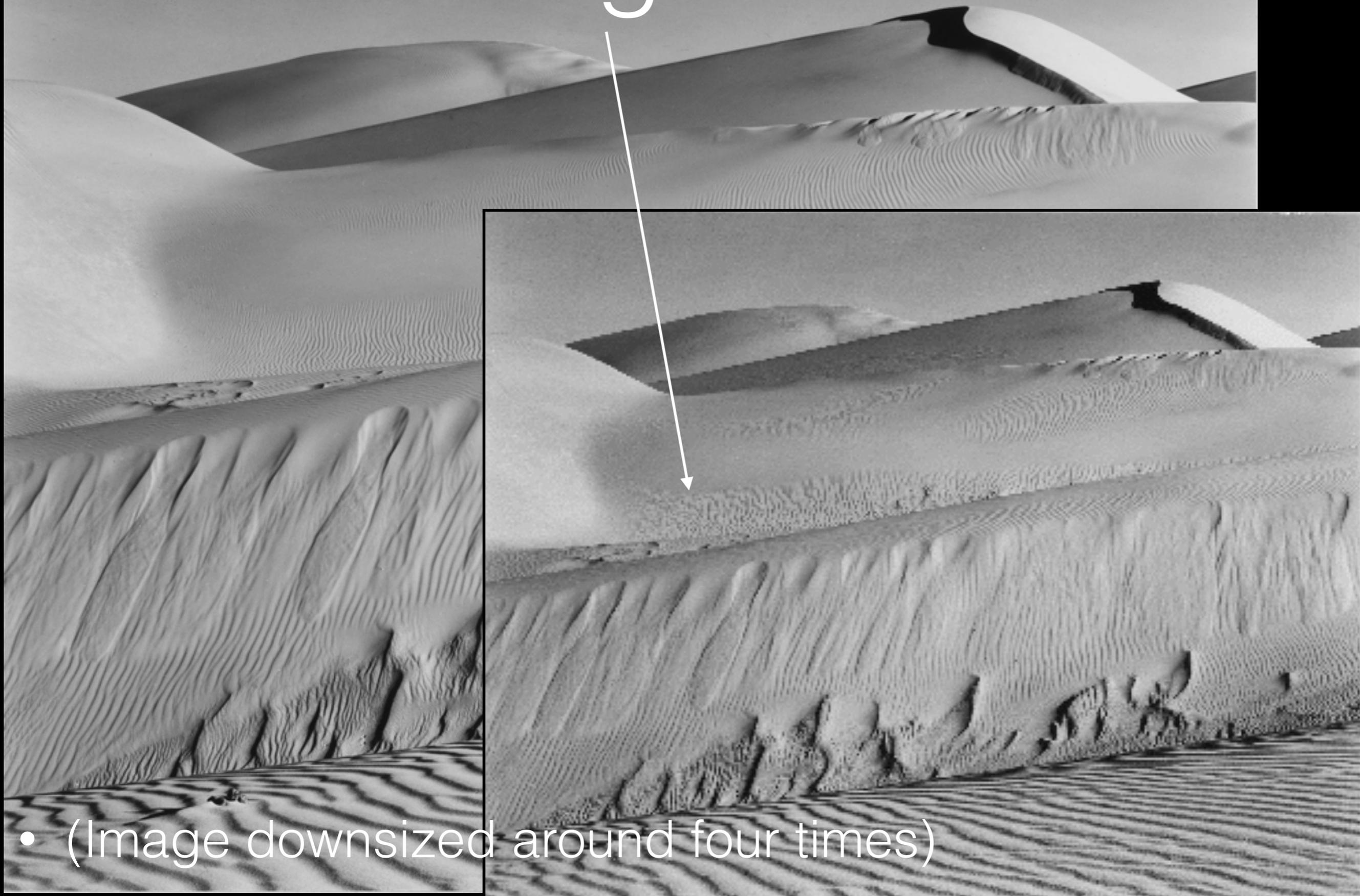
Nyquist sampling
= twice the frequency



Aliasing

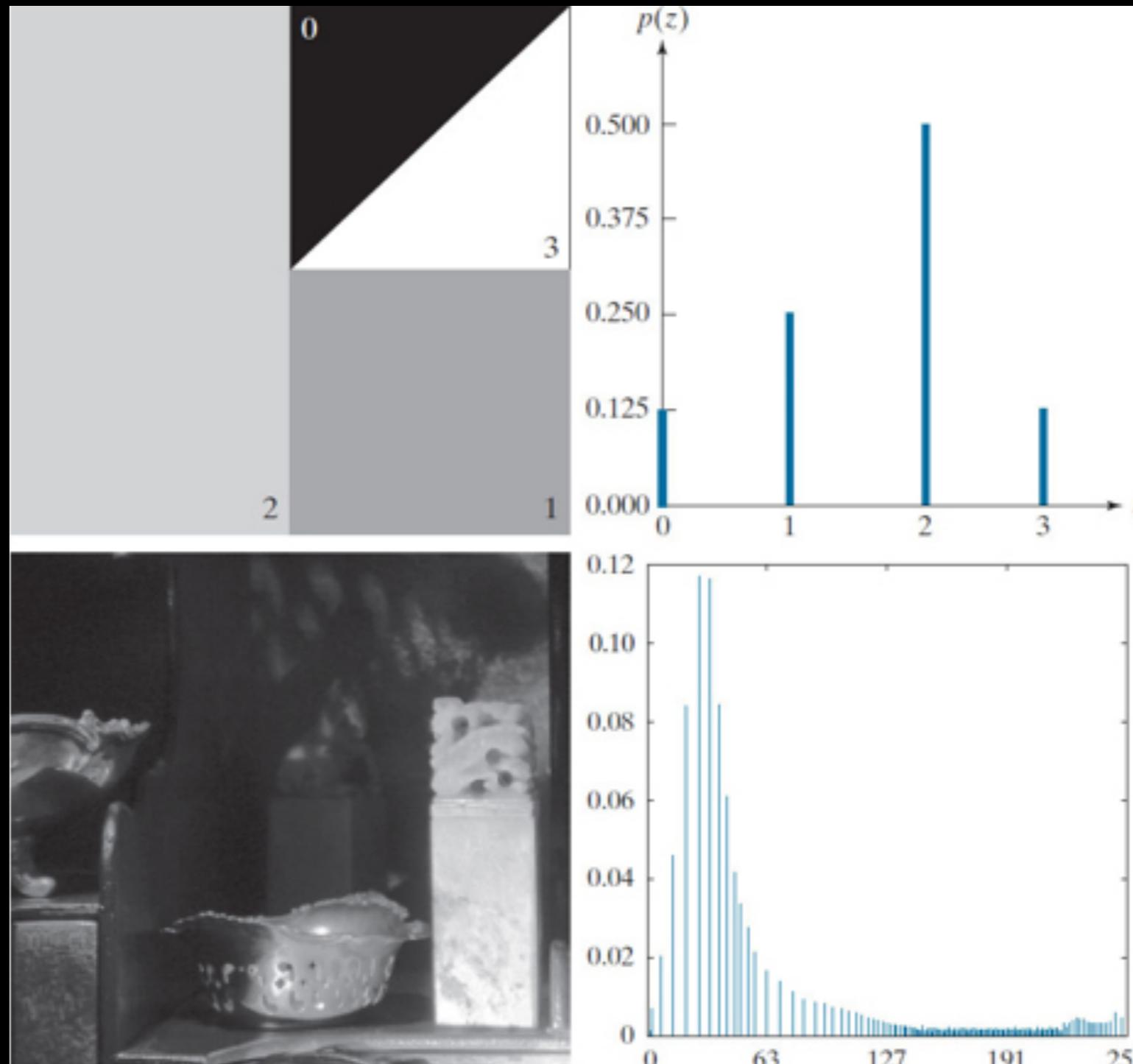


Aliasing

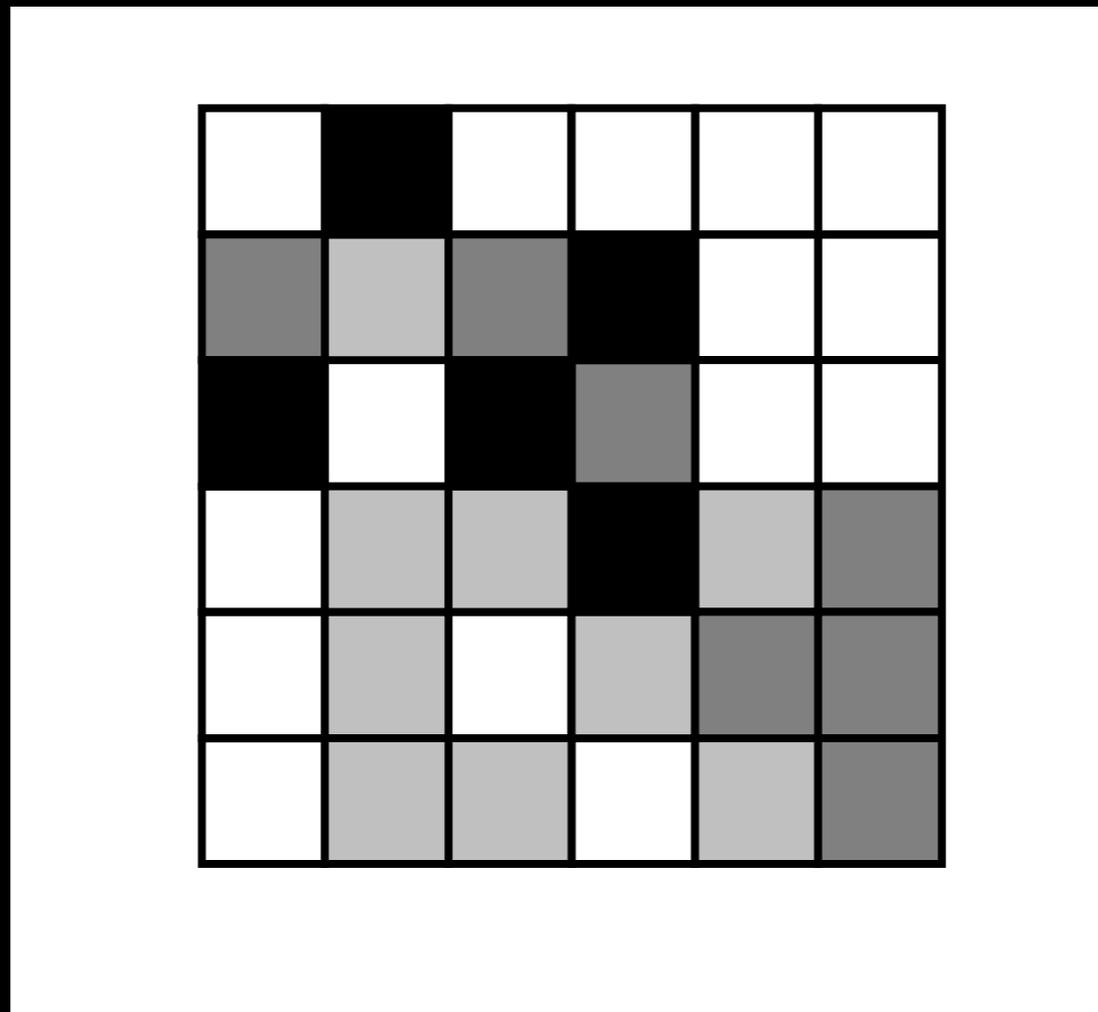


- (Image downsized around four times)

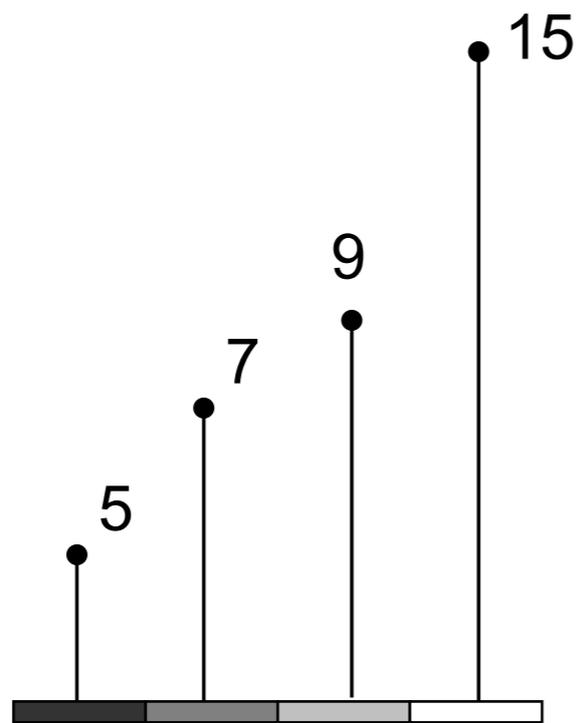
Histogram shows distribution of gray-levels in an image



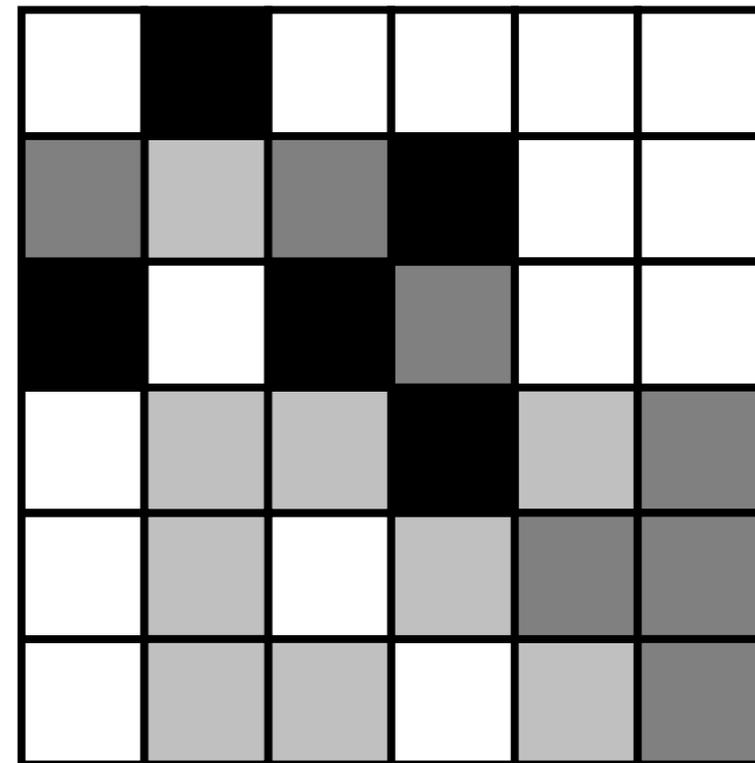
Lets plot the histogram of
this synthetic image



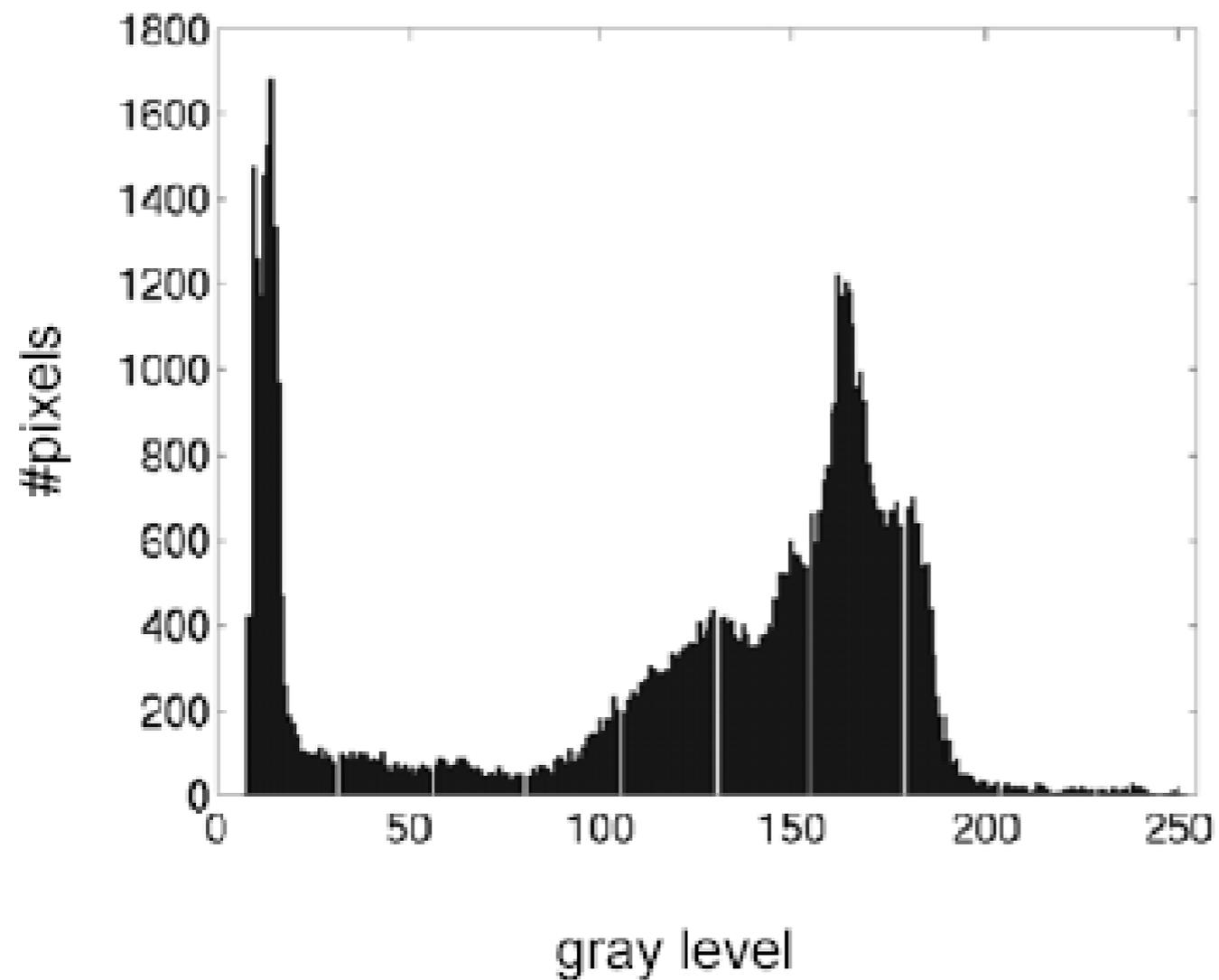
Histogram:



Graylevel

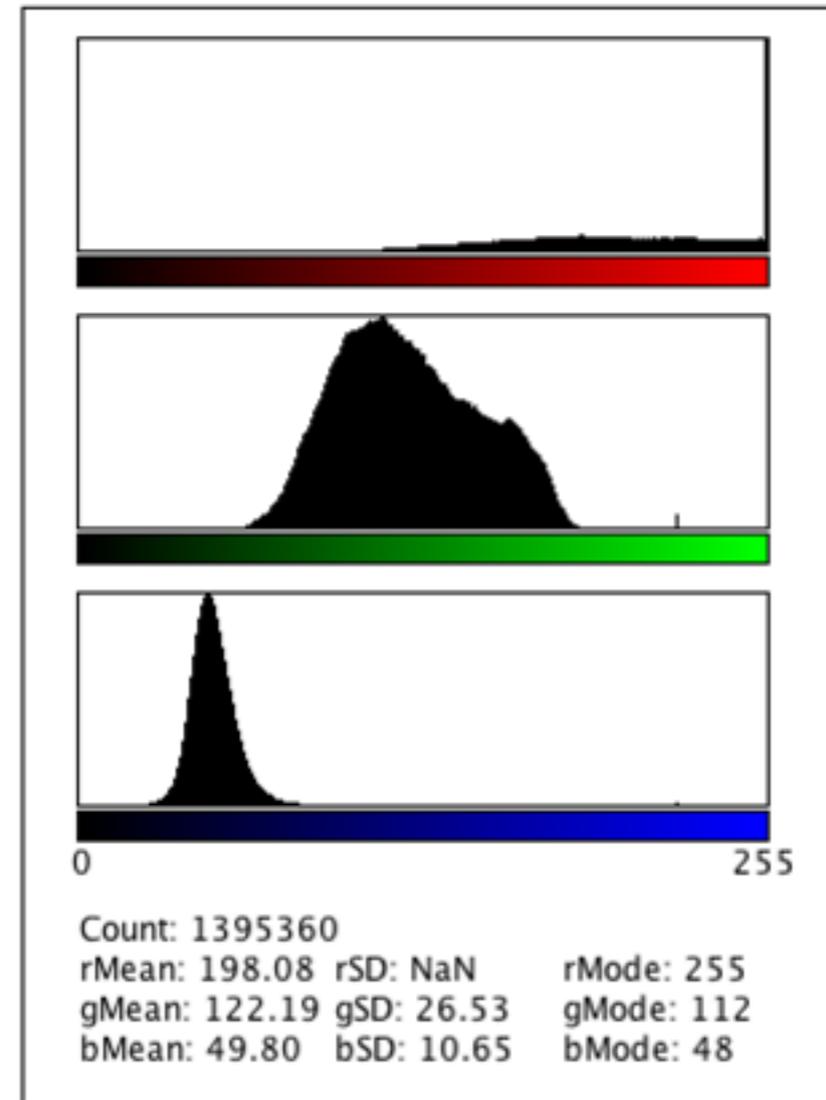


Grayscale Histogram



Cameraman
image

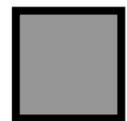
Color Histogram



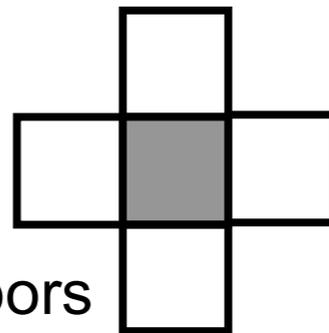
[List](#) [Copy](#) :

Image enhancement

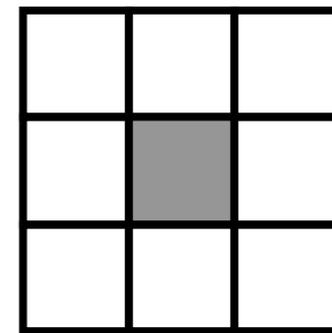
- In the pixel domain, for example:



Pixel



4-Neighbors

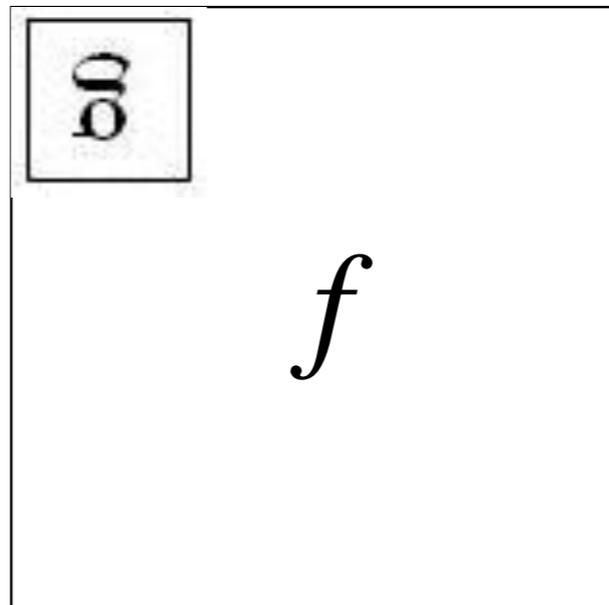


8-Neighbors

Convolution

- Let f be the image and g be the kernel. The output of convolving f with g is denoted $f * g$.

$$(f * g)[m, n] = \sum_{k, l} f[m - k, n - l] g[k, l]$$



- Convention: kernel is “flipped”
- MATLAB: conv2 vs. filter2 (also imfilter)

Convolution properties

- **Linearity:** $\text{filter}(f_1 + f_2) = \text{filter}(f_1) + \text{filter}(f_2)$
- **Shift invariance:** same behavior regardless of pixel location: $\text{filter}(\text{shift}(f)) = \text{shift}(\text{filter}(f))$
- Theoretical result: any linear shift-invariant operator can be represented as a convolution

“Drag-and-Stamp”

- Local linear operations on an image

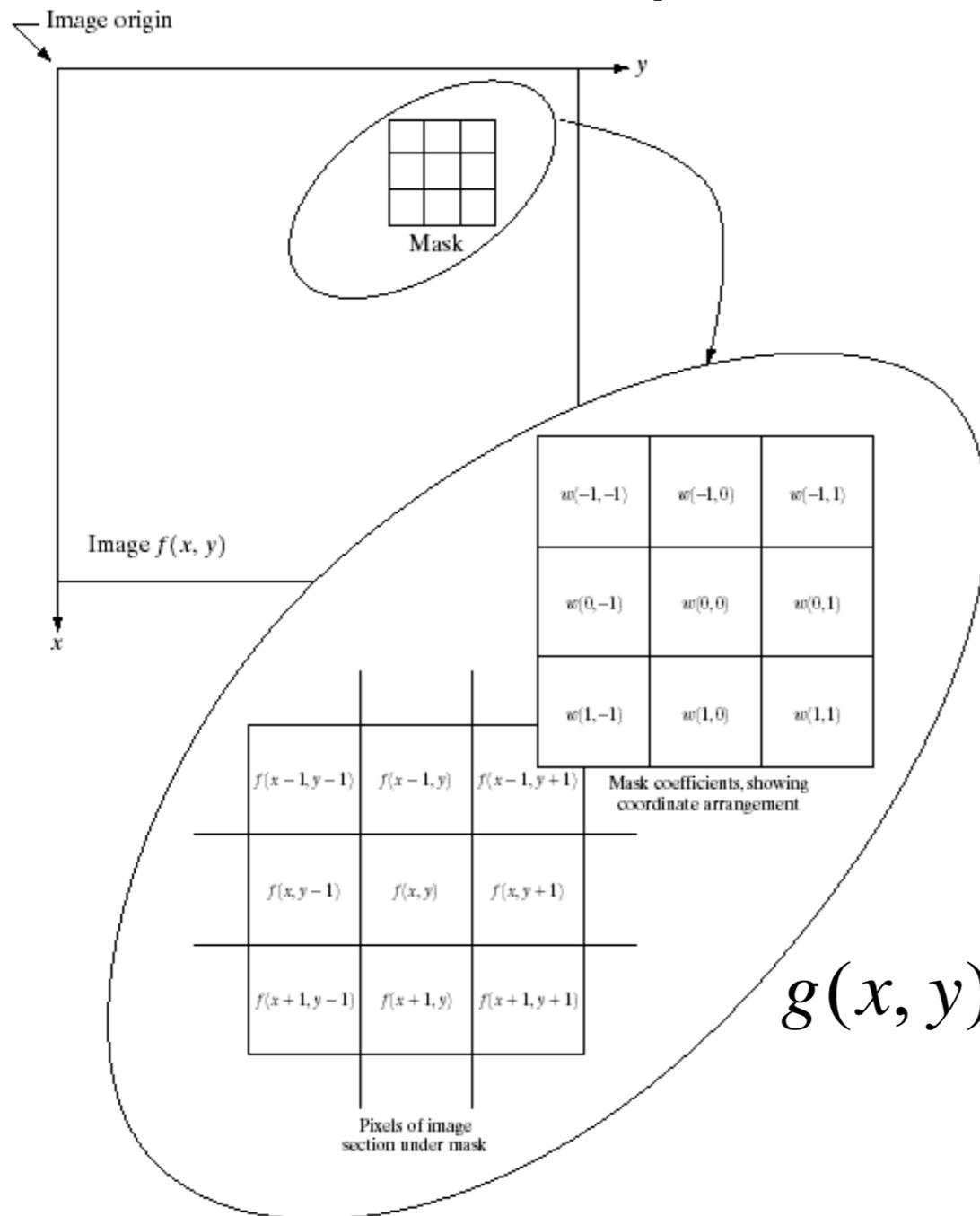


FIGURE 3.32 The mechanics of spatial filtering. The magnified drawing shows a 3×3 mask and the image section directly under it; the image section is shown displaced out from under the mask for ease of readability.

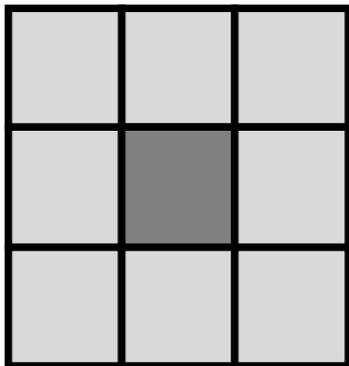
w_1	w_2	w_3
w_4	w_5	w_6
w_7	w_8	w_9

Input: $f(x, y)$, Output: $g(x, y)$

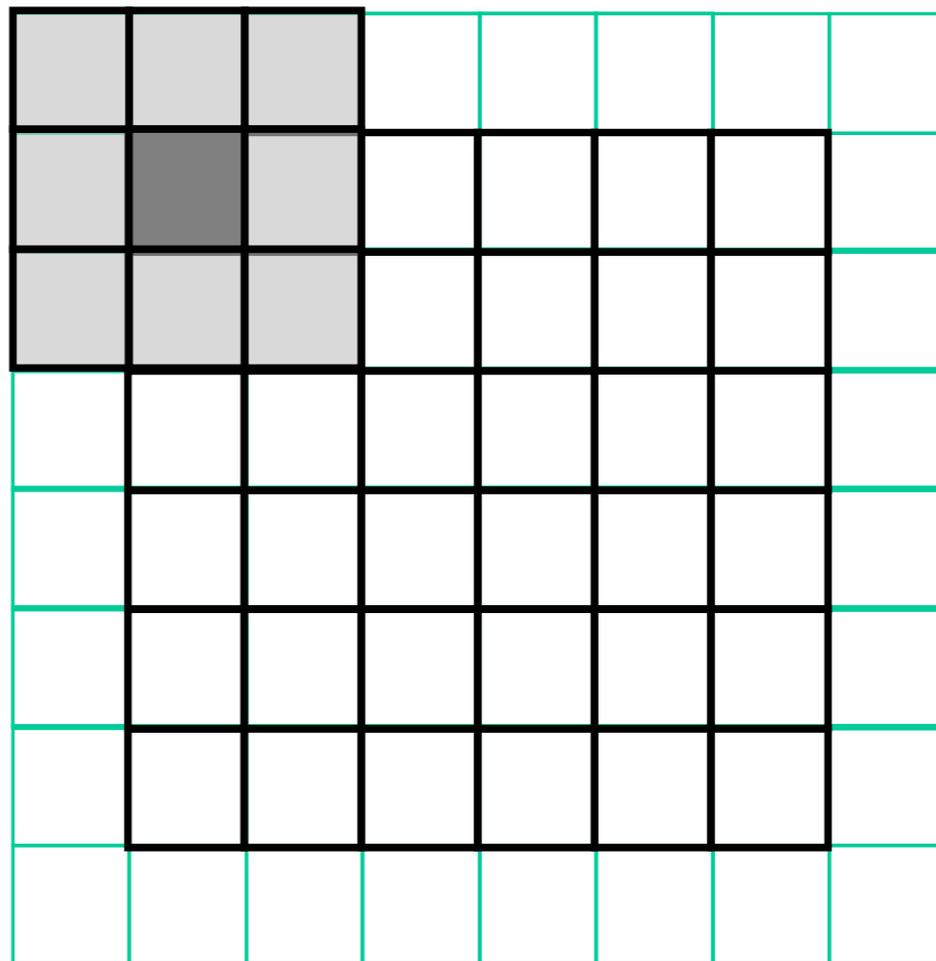
$$g(x, y) = w_1 f(x-1, y-1) + w_2 f(x-1, y) + \dots + w_8 f(x+1, y-1) + w_9 f(x+1, y+1)$$

What to do at the edges of the image

- An important point: **Edge Effects**
 - To compute all pixel values in the output image, we need to fill in a “border”



Mask dimension = $2M+1$



Border dimension = M

Image Enhancement: Spatial Filtering Operation

- An important point: **Edge Effects** (Ex.: 5x5 Mask)

– How to fill in a “border”

- Zeros (Ringing)
- Replication (Better)
- Reflection (“Best”)

d	c	a	b						
b	a	a	b						
b	a	a	b						
d	c	c	d						

- **Procedure:**

- Replicate row-wise
- Replicate column-wise
- Apply filtering
- Remove borders

MATLAB methods:

- clip filter (black): `imfilter(f, g, 0)`
- wrap around: `imfilter(f, g, 'circular')`
- copy edge: `imfilter(f, g, 'replicate')`
- reflect across edge: `imfilter(f, g, 'symmetric')`

What happens:

- Filter kernel operations on matrix (image)
- “Drag and Stamp” operation
- Using MATLAB: `filter2(A,B)`
 - use: 'same', 'valid' and 'full' parameters
(ex: `filter2(A,B,'full')`)

Filtering example

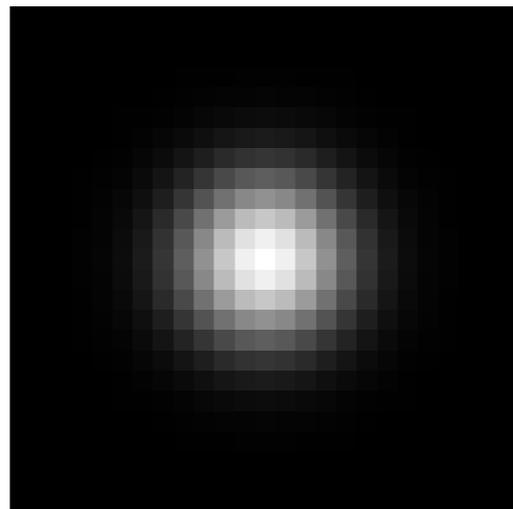
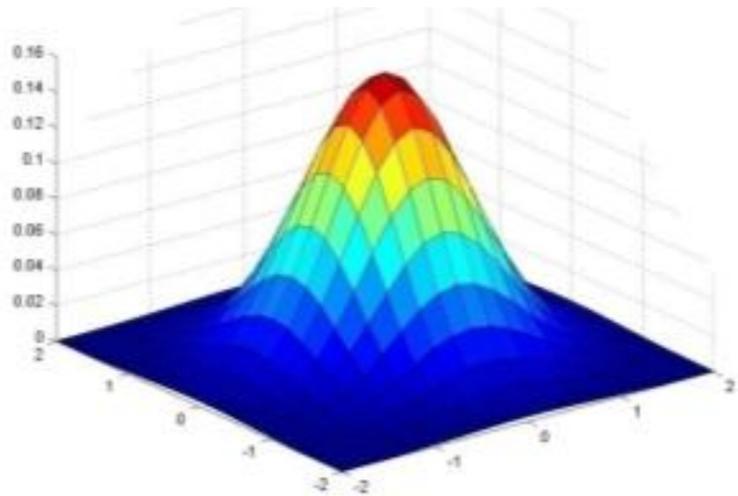
- MATLAB code how to apply filter kernel:

Gaussian blur filtering

- Filter with Gaussian kernel
- Filtering twice with a certain Gaussian is the same as filtering with this Gaussian convolved with itself -> MORE BLUR

Gaussian Kernel

$$G_{\sigma} = \frac{1}{2\pi\sigma^2} e^{-\frac{(x^2+y^2)}{2\sigma^2}}$$



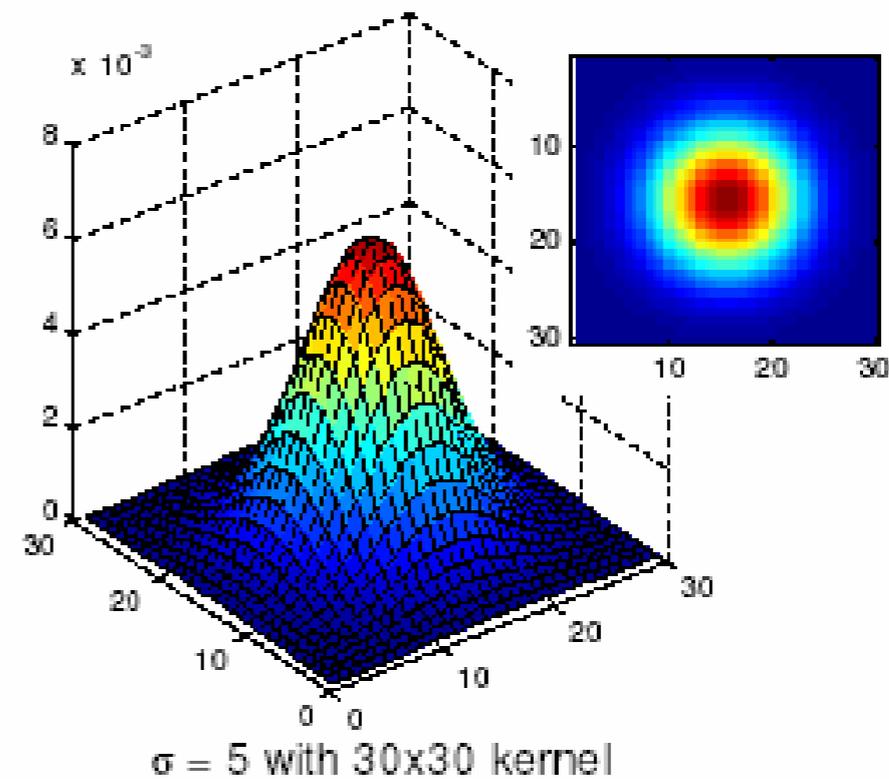
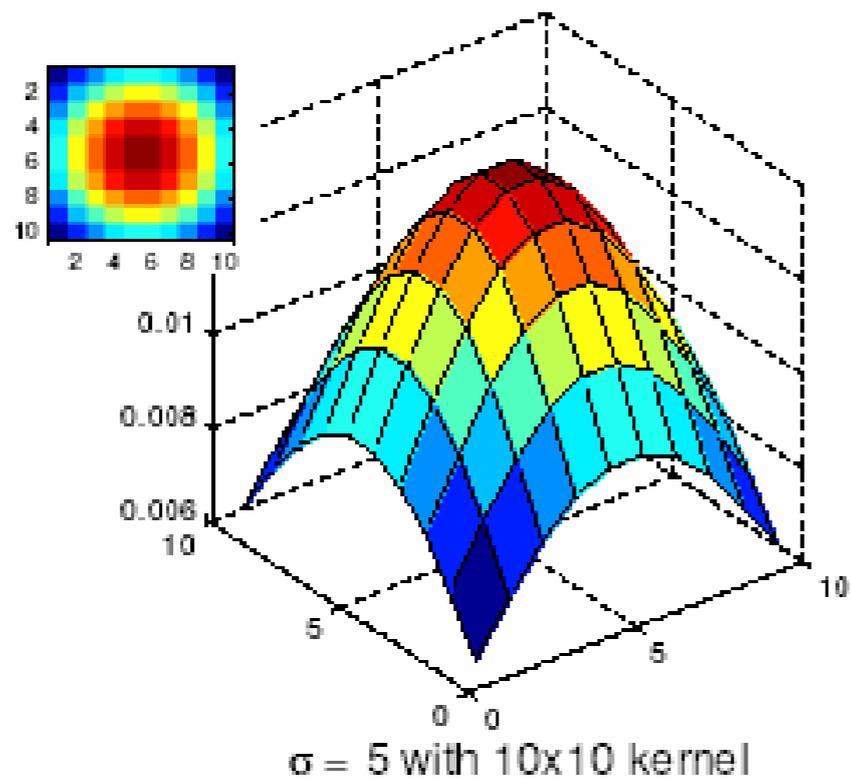
0.003	0.013	0.022	0.013	0.003
0.013	0.059	0.097	0.059	0.013
0.022	0.097	0.159	0.097	0.022
0.013	0.059	0.097	0.059	0.013
0.003	0.013	0.022	0.013	0.003

5 x 5, $\sigma = 1$
fspecial('gauss',5,1)

- Constant factor at front makes volume sum to 1 (can be ignored, as we should re-normalize weights to sum to 1 in any case)

Choosing kernel width

- Gaussian filters have infinite support, but discrete filters use finite kernels



Example code MATLAB

```
ImageO = imread('MushroomDownload.jpg');  
Image = ImageO(:,:,1);
```

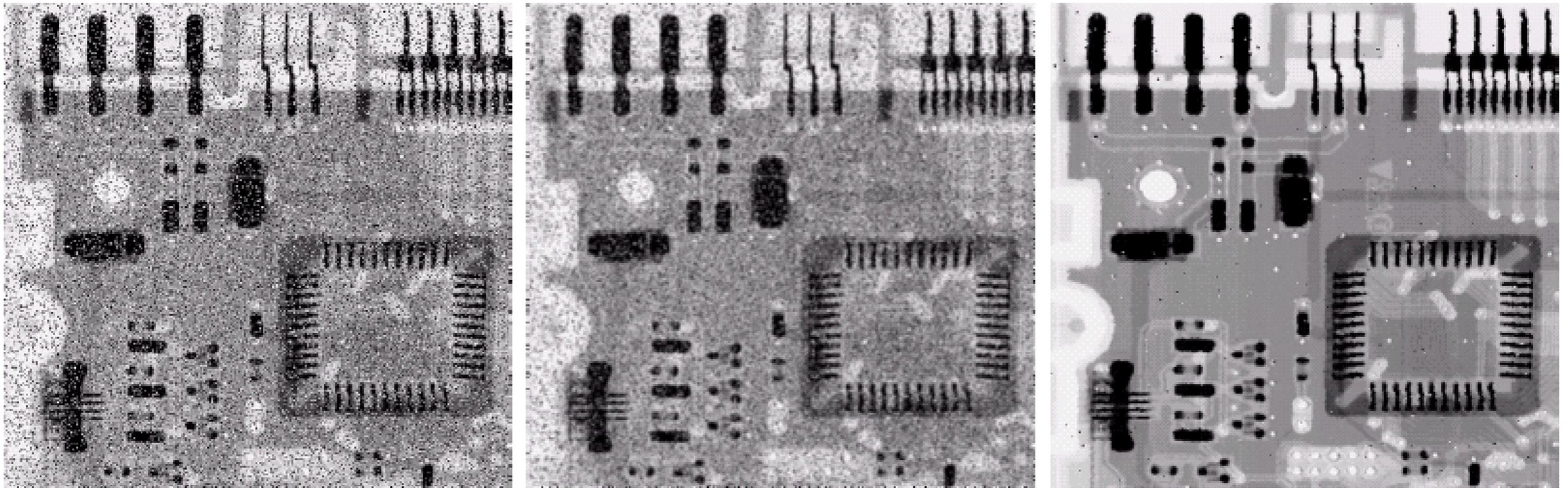
```
H = fspecial('motion',20,45);
```

```
MotionBlur = imfilter(Image,H,'replicate');
```

```
subplot(2,1,2), imagesc(MotionBlur),axis equal, axis off,  
colormap gray
```

```
subplot(2,1,1), imagesc(Image),axis equal, axis off, colormap  
gray
```

Blurring can be used for denoising



a b c

FIGURE 3.37 (a) X-ray image of circuit board corrupted by salt-and-pepper noise. (b) Noise reduction with a 3×3 averaging mask. (c) Noise reduction with a 3×3 median filter. (Original image courtesy of Mr. Joseph E. Pascente, Lixi, Inc.)

- (Example from course textbook Gonzales & Wood)

Try this out on noisy data
with median, gaussian etc...

Note: it's better to vectorize your code in MATLAB

```
tic
for t = 1:1024
    y(t) = sin(2*pi*t/512);
end
toc
```

```
tic
y = sin(pi*(0:(1/256):2));
toc
```

You can read up on this at:

http://www.mathworks.com/help/matlab/matlab_prog/vectorization.html

Fourier Transform

- Examples of spatial filtering in frequency space

Some Fourier Transform Pairs

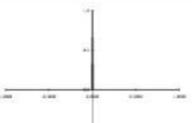
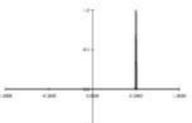
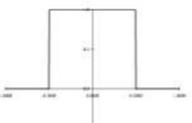
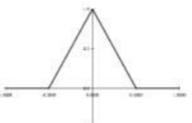
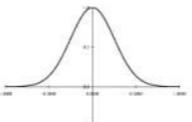
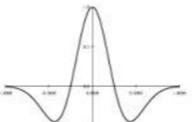
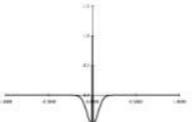
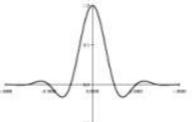
Name	Signal	Transform
impulse	 $\delta(x)$	1
shifted impulse	 $\delta(x - u)$	$e^{-j\omega u}$
box filter	 $\text{box}(x/a)$	$a\text{sinc}(a\omega)$
tent	 $\text{tent}(x/a)$	$a\text{sinc}^2(a\omega)$
Gaussian	 $G(x; \sigma)$	$\frac{\sqrt{2\pi}}{\sigma} G(\omega; \sigma^{-1})$
Laplacian of Gaussian	 $(\frac{x^2}{\sigma^4} - \frac{1}{\sigma^2})G(x; \sigma)$	$-\frac{\sqrt{2\pi}}{\sigma} \omega^2 G(\omega; \sigma^{-1})$
Gabor	 $\cos(\omega_0 x)G(x; \sigma)$	$\frac{\sqrt{2\pi}}{\sigma} G(\omega \pm \omega_0; \sigma^{-1})$
unsharp mask	 $(1 + \gamma)\delta(x) - \gamma G(x; \sigma)$	$(1 + \gamma) - \frac{\sqrt{2\pi}\gamma}{\sigma} G(\omega; \sigma^{-1})$
windowed sinc	 $\text{rcos}(x/(aW)) \text{sinc}(x/a)$	(see Figure 3.29)

Table: Richard Szeliski, *Computer Vision and Applications*, Springer, 2010, ISBN 978-1-84882-935-0, p.137, <http://szeliski.org/Book/>.

Fourier Transform Pairs

Function, f(t)	Fourier Transform, F(ω)
<i>Definition of Inverse Fourier Transform</i> $f(t) = \frac{1}{2\pi} \int_{-\infty}^{\infty} F(\omega) e^{j\omega t} d\omega$	<i>Definition of Fourier Transform</i> $F(\omega) = \int_{-\infty}^{\infty} f(t) e^{-j\omega t} dt$
$f(t - t_0)$	$F(\omega) e^{-j\omega t_0}$
$f(t) e^{j\omega_0 t}$	$F(\omega - \omega_0)$
$f(\alpha t)$	$\frac{1}{ \alpha } F\left(\frac{\omega}{\alpha}\right)$
$F(t)$	$2\pi f(-\omega)$
$\frac{d^n f(t)}{dt^n}$	$(j\omega)^n F(\omega)$
$(-jt)^n f(t)$	$\frac{d^n F(\omega)}{d\omega^n}$
$\int_{-\infty}^t f(\tau) d\tau$	$\frac{F(\omega)}{j\omega} + \pi F(0) \delta(\omega)$
$\delta(t)$	1
$e^{j\omega_0 t}$	$2\pi \delta(\omega - \omega_0)$
$\text{sgn}(t)$	$\frac{2}{j\omega}$

Function, f(t)	Fourier Transform, F(ω)
$j \frac{1}{\pi t}$	$\text{sgn}(\omega)$
$u(t)$	$\pi \delta(\omega) + \frac{1}{j\omega}$
$\sum_{n=-\infty}^{\infty} F_n e^{jn\omega_0 t}$	$2\pi \sum_{n=-\infty}^{\infty} F_n \delta(\omega - n\omega_0)$
$\text{rect}\left(\frac{t}{\tau}\right)$	$\tau \text{Sa}\left(\frac{\omega\tau}{2}\right)$
$\frac{B}{2\pi} \text{Sa}\left(\frac{Bt}{2}\right)$	$\text{rect}\left(\frac{\omega}{B}\right)$
$\text{tri}(t)$	$\text{Sa}^2\left(\frac{\omega}{2}\right)$
$A \cos\left(\frac{\pi t}{2\tau}\right) \text{rect}\left(\frac{t}{2\tau}\right)$	$\frac{A\pi}{\tau} \frac{\cos(\omega\tau)}{\left(\frac{\pi}{2\tau}\right)^2 - \omega^2}$
$\cos(\omega_0 t)$	$\pi [\delta(\omega - \omega_0) + \delta(\omega + \omega_0)]$
$\sin(\omega_0 t)$	$\frac{\pi}{j} [\delta(\omega - \omega_0) - \delta(\omega + \omega_0)]$
$u(t) \cos(\omega_0 t)$	$\frac{\pi}{2} [\delta(\omega - \omega_0) + \delta(\omega + \omega_0)] + \frac{j\omega}{\omega_0^2 - \omega^2}$
$u(t) \sin(\omega_0 t)$	$\frac{\pi}{2j} [\delta(\omega - \omega_0) - \delta(\omega + \omega_0)] + \frac{\omega^2}{\omega_0^2 - \omega^2}$
$u(t) e^{-\alpha t} \cos(\omega_0 t)$	$\frac{(\alpha + j\omega)}{\omega_0^2 + (\alpha + j\omega)^2}$

Lets do an experiment with spatial frequency imaging

- Take an image of the line pairs with your cell phone
- If you don't have one, come up here and take them with a camera
- Download to your computer and Fourier transform the data. Can you recognize the spatial frequencies from the image?

